

Contents

Preface.....	v
Contents.....	vii
Chapter 1. Application of resonant systems	
§1.1 Load relief and balancing of robotic systems.....	1
§1.2 Systems to relieve drives from inertia forces.....	9
§1.3 Resonant robotic system components.....	19
§1.4 Synthesis of spring accumulators.....	36
§1.5 Design of resonant robotic systems.....	53
Chapter 2. Dynamics of resonant robotic systems	
§2.1 Equations of motion for resonant robots.....	69
§2.2 Resonant systems with ideal drives.....	84
§2.3 Electromechanical drive for resonant systems.....	89
Chapter 3. Optimal control of resonant systems	
§3.1 Statement of the optimisation problem. Efficiency criteria.....	93
§3.2 Synthesis of optimal cyclic drive.....	99
§3.3 Control of resonant drives with minimal energy consumption.....	109
§3.4 Operating speed of cyclic resonant drives.....	115
§3.5 Optimal control with minimal heat generation.....	120
§3.6 Control to minimise cumulative angular momentum of the driver.....	131
§3.7 Efficiency of control for resonant drives.....	142
Chapter 4. Adaptive control of resonant robots	
§4.1 Introduction.....	147
§4.2 Synthesis of regulator.....	148
§4.3 Adaptive control.....	153
§4.4 Simultaneous control of rotation and translation.....	157
§4.5 Conclusion.....	161
Bibliography.....	163
Subject Index.....	169