

Contents

Preface	IX
Preface to the English Edition	X
Preface to the Second Edition	XII
Preface to the First Edition	XV
References	XIX
1 Object of Analysis and Problem of Modelling	1
1.1 Multidimensionality and Multifunctionality	1
1.2 Principal Factors taken into Account During Creation of Design Models	3
1.3 Incomplete Determinacy of an Object's Knowledge	6
1.4 Experiment and Practical Experience	7
1.5 General Issues of Modelling	10
1.6 Majorant and Minorant Models	12
1.7 Posterior Analysis of a Design Model	13
References	15
2 Building a Design Model	17
2.1 Determinative Parameters and the Number of Degrees of Freedom	18
2.2 Model of Loading as a Part of the Design Model	22
2.3 Validation and Means of Description of design Models	25
2.4 Some Tricks	34
2.5 Mono-Constraints and Poly-Constraints in Design Models	42
2.6 Perfectly Rigid Bodies as Finite Element Types	46
2.6.1 One-Dimensional Perfectly Rigid bodies	47
2.6.2 Two-Dimensional Perfectly Rigid bodies	47
2.6.3 Three-Dimensional Perfectly Rigid bodies	48
2.7 On a Nonlinear Analysis	51
2.8 Using Several Models at the same Time	54
2.9 Comparison between Calculated and Experimental Data	59
References	62

3 Basic Relationships for Discrete Systems	65
3.1 Governing Equations	65
3.1.1 Slope Deflection Method	67
3.1.2 Force Method	71
3.1.2 Duality of the Slope Deflection Method and Force Method Projectors	73
3.2 Static and Kinematical Analysis	77
3.2.1 Note on Dislocations	81
3.3 Poly-constraints Revisited. Variational Formulation	82
3.4 Null-Elements	91
3.5 Geometrical Nonlinearity. Stability	98
3.5.1 Four Floors of Geometrically Nonlinear Problem Statements	98
3.5.2 Geometrical Nonlinearity in Truss-type Bars	99
3.5.3 Geometrical Nonlinear Equations in Variations	105
3.6 Structural Nonlinearity – Systems with Unilateral Constraints	109
3.7 Cable Elements in Design Models	114
3.7.1 Coordinate Axes	118
3.7.2 Specification of Pre-stress	119
3.7.3 On Linearized Models of Cable Structures	120
3.7.4 Linearization of Cable Elements in a Design Model	122
3.7.5 Linearization of Compressed and Bent Elements of aDesign Model	126
3.8 Dynamical Analysis	128
3.9 Continual Systems in Finite-Dimensional Representation.....	133
3.9.1 A Note on Terminology	135
3.9.2 A Note on Method of Visualization Design Models	135
References	136
4 Finite Element Models	139
4.1 Notes on a Structural Discretization	139
4.2 Basic Concepts of the Finite Element Analysis	140
4.3 Modelling of Bar Systems	144
4.4 Finite Element Grid Modelling	151
4.5 On Practical Convergence	153
4.6 Convergence Validation for some Models	154
4.7 Richardson Extrapolation	158
4.8 Circumventing Singularities	161
4.9 Finite Element Mesh Generation	165
4.9 Using Hybrid Finite Elements	169
References	173

5 Mistakes and Pitfalls, Special Techniques to Build Finite Element Models	177
5.1 Fragmentation	177
5.2 Building Continuous Stress Fields with FEM	184
5.3 Mistakes and Traps in Coupling Elements of Different Dimensionality	193
5.3.1 Bars + Plates	194
5.3.2 Bars + Plane Stress	200
5.3.3 Bars + Massive Elements	211
5.3.4 Plane Stress + Flexural Plates (Coupling Shell Elements) ..	211
5.4 A Paradox of Coupling Bernoulli and Timoshenko Bars in the Same Model	216
5.5 Approximating Geometric Shapes and Fixations	224
5.6 Computational Error and Ways to Dispose of it	227
5.6.1 Notes on the Super-Element Application	238
5.6.2 Notes on a Software Testing	239
5.7 Step-by-Step Procedure	241
References	246
6 Estimating and Interpreting Results	249
6.1 An Estimation Issue	249
6.2 What analysis results are Needed	250
6.3 General Validation	256
6.4 Characteristic Displacement	259
6.5 Calculating Energy of Deformation	262
6.6 Further Processing of Results	264
References	266
7 Uncertainty of Parameters	267
7.1 Key Sources of Uncertainty	267
7.2 Methods of Sensitivity Analysis	274
7.3 Sensitivity of Natural Oscillations	277
7.4 Estimating Extra Stresses Caused by Varied Stiffness	282
7.5 Theoretical Estimates in the Case of Uncertain Stiffness Properties	285
7.6 Making Use of Experiment Planning Methods	287
7.7 Limit Equilibrium under an Uncertain Load	294
References	296

8 A Review of some Problem Classes	299
8.1 Hinged Bar System	299
8.2 Erection	302
8.2.1 Genetic Nonlinearity	307
8.3 Pre-stressing	315
8.4 Structures with Hydraulic Jacks	318
8.4.1 Liquid Finite Element	323
8.5 A "Structure – Foundation" Model	324
8.5.1 Allowing for a Distributive Ability of Soil	324
8.5.2 A Two-parametric Bed Model	326
8.6 Assigning Properties of a Two-parametric Elastic Bed	331
8.6.1 A "CCC" Bed Model	334
8.7 Employing Finite-Element Foundation Models	342
8.8 A Bi-member Model of an Open-section Thin-walled Bar	345
8.8.1 Construction of a Bi-member Model	345
8.8.2 A Bi-member Model of a Thin-walled Bar Reinforced by Lateral Slats	351
8.8.3 A Thin-walled Bar Reinforced by a Lateral Diaphragm ..	357
8.8.4 A Mathematical Interpretation of the Bi-member Model and its Discrete Scheme	358
8.9 Design Load Combinations	361
References	367
9 Buckling Problems and Related Issues	369
9.1 Validating an Equilibrium Stability	369
9.2 Classical Problems of Equilibrium Stability	375
9.3 Free Lengths of Compressed Bars	379
9.4 Analysis of a Role Played by Particular Subsystems	383
9.5 On the Influence of Additional Constraints upon the Stability of a System	388
9.5.1 On an Error of a Mysterious Nature that Happens in Software when Analyzing Mechanical Systems for Buckling	389
9.6 On a Paradox Encountered in a Bar Buckling Problem	404
9.7 Allowing for Imperfections in a Real Construction	410
9.8 Notes for Allowing for P - Δ Effects	415
References	416
10 Problems of Dynamics	419
10.1 Design Models for Dynamical analysis	419
10.1.1 Dynamical Degrees of Freedom	423

10.1.2 Dynamic Condensation – a Guyan's Procedure	424
10.2 Integrating Motion Equations	427
10.3 Forced Oscillations under a Harmonic Action	432
10.3.1 A Model by Gordeyeva	439
10.4 Decrement of Oscillations	443
10.4.1 Finite Elements of an Elastic Material	446
10.4.2 A Dry Friction Element	447
10.4.3 A Viscous Friction Element	447
10.4.4 A nonlinear Viscous Friction Element	448
10.4.5 Damping by Radiation	448
10.5 Three Resonance Curves	450
10.6 Analysis of Structures under Seismic Actions	452
10.6.1 Earthquake Spectra	452
10.6.2 Seismic Response	453
10.6.3 Analysis with Accelerograms	459
10.6.4 Story Response Spectra	459
10.7 Action of Pulse and Impact Loads	461
10.8 Oscillations under an Action of Wind Flow Pulsations	465
10.8.1 Modelling of Wind Actions	465
10.8.2 A Dynamic Action of the Wind Load's Pulsation Component	466
10.8.3 Representation of a Pulsation Component of a Wind Load	468
10.8.4 Spectrum of Wind Velocity Pulsations	470
10.8.5 A Dynamical Component of a Design Factor	471
10.8.6 Issues of Numerical Implementation	472
References	474

11 A Word Instead of a Conclusion 477

11.1 Our Recommendations to Potential Users	471
References	483

Appendix 485

A.1 Jordan Exclusions and their Role in Structural Mechanics	486
A.2 General Description	486
A.3 Jordan Exclusions with the Stiffness Matrix of a Structure	488
A.4 Stiffness Matrix of a Finite Element Non-Rigidly Attached to its Nodes	493
A.5 A Double Jordan Exclusion	496
References	498

VIII Contents

Index

499