

Contents

Preface	vii
1 Introduction	1
1.1 Scope of this Monograph	2
1.2 Useful Background for this Presentation	3
1.3 Overview	4
2 Finite Element Formulations in Nonlinear Solid Mechanics	7
2.1 Initial/Boundary Value Problems in the Kinematically Linear Regime	8
2.1.1 Strong Form of the IBVP	9
2.1.2 Weak Form of the IBVP	15
2.2 The IBVP in the Finite Strain Case	17
2.2.1 Notation and Problem Formulation	17
2.2.2 Finite Strain Kinematics	18
2.2.3 Stress Definitions Appropriate for Large Deformations	24
2.2.4 Frame Indifference	27
2.2.5 The Strong Form in Finite Strains	31
2.2.6 The Weak Form in Finite Strains	39
2.3 Finite Element Discretization	41
2.3.1 Discretized Weak Form; Generation of Discrete Non-linear Equations	43
2.3.2 Discrete Nonlinear Equations for the Kinematically Linear Case	46

2.4	Solution Strategies for Spatially Discrete Systems	48
2.4.1	Quasistatics and Incremental Load Methods	48
2.4.2	Dynamics and Global Time Stepping Procedures	50
2.4.3	Local (Constitutive) Time Stepping Procedures	54
2.4.4	Nonlinear Equation Solving	56
2.4.5	Consistent Algorithmic Linearization of Material Response	61
3	The Kinematically Linear Contact Problem	69
3.1	Strong Forms in Linearized Frictionless Contact	70
3.1.1	The Signorini Problem: Contact with a Rigid Obstacle	70
3.1.2	The Two Body Contact Problem	75
3.2	Weak Statements of the Contact Problem	79
3.2.1	Variational Inequalities	81
3.2.2	The Quasistatic Elastic Case: Contact as a Problem of Constrained Optimization	83
3.3	Methods of Constraint Enforcement	85
3.3.1	Classical Lagrange Multiplier Methods	85
3.3.2	Penalty Methods	89
3.3.3	Augmented Lagrangian Methods	91
3.4	Inclusion of Friction into the Problem Description	94
3.4.1	Friction Kinematics and Traction Measures	94
3.4.2	Unregularized Coulomb Friction Laws	96
3.4.3	Regularization of Friction	98
3.4.4	Variational Statements Including Friction	101
3.4.5	Nonlocal Frictional Descriptions	106
4	Continuum Mechanics of Large Deformation Contact	109
4.1	Two Body Contact Problem Definition	110
4.1.1	Local Momentum Balances	111
4.1.2	Initial and Boundary Conditions	112
4.2	Contact Constraints in Large Deformations	113
4.2.1	The Gap Function as Defined by Closest Point Projection	113
4.2.2	Frictional Kinematics on Interfaces	116
4.2.3	Frame Indifference of Contact Rate Variables	121
4.2.4	Coulomb Friction in Large Sliding	129
4.3	Summary: Strong Form of the Large Deformation Contact Problem	134
4.4	Virtual Work Expressions Incorporating Contact	137
4.4.1	Contact Virtual Work: The Contact Integral	139
4.4.2	Linearization of Contact Virtual Work	141
4.4.3	Summary: Weak Form of the Large Deformation Contact Problem	144

5	Finite Element Implementation of Contact Interaction	145
5.1	Finite Dimensional Representation of Contact Interaction	147
5.1.1	Contact Surface Discretization	147
5.1.2	Numerical Integration of the Contact Integral	148
5.1.3	Contact Detection (Searching)	152
5.2	Time Discretization	158
5.2.1	Global time integration schemes	158
5.2.2	Temporally Discrete Frictional Laws for the Penalty Regularized Case	159
5.3	Contact Stiffness and Residual: Penalty Regularized Case	162
5.3.1	Three dimensional matrix expressions	162
5.3.2	Two dimensional matrix expressions	166
5.4	Augmented Lagrangian Constraint Enforcement Algorithms	169
5.4.1	Uzawa's Method (Method of Multipliers)	170
5.4.2	Algorithmic Symmetrization Using Augmented Lagrangians	174
5.4.3	Augmented Lagrangian Discrete Force and Stiffness Expressions	178
5.5	Numerical Examples	180
5.5.1	General Demonstrations of the Computational Framework	180
5.5.2	Demonstrations of Augmented Lagrangian Algorithmic Performance	196
6	Tribological Complexity in Interface Constitutive Models	211
6.1	Rate and State Dependent Friction	212
6.1.1	Motivation	213
6.1.2	One Dimensional Model Development	215
6.1.3	Model Incorporation into Convective Slip Advected Frame	220
6.1.4	Local Time Stepping Algorithm	222
6.1.5	Contact Force Vector and Stiffness Matrix	226
6.1.6	Numerical Examples	227
6.2	Thermomechanically Coupled Friction on Interfaces	238
6.2.1	Motivation	239
6.2.2	Thermally Coupled Problem Definition	241
6.2.3	A Thermodynamically Consistent Friction Model	244
6.2.4	Variational Principle and Finite Element Implementation	255
6.2.5	Numerical Examples	269
6.3	Thermodynamical Algorithmic Consistency	279
6.3.1	Constitutive Framework for Bulk Continua	280
6.3.2	Thermomechanical Interface Model Framework	283
6.3.3	<i>A Priori</i> Stability Estimates for Dynamic Frictional Contact	286

6.3.4	A New Partitioned Scheme for Thermomechanical Contact	289
6.3.5	Algorithmic Treatment of Contact Conditions According to the Adiabatic Split	291
7	Energy-Momentum Approaches to Impact Mechanics	295
7.1	Energy Stability of Traditional Schemes	297
7.1.1	A Model System	297
7.1.2	The Concept of Energy Stability	299
7.1.3	Influence of Contact Constraints on System Energy	300
7.2	Energy-Momentum Methods for Elastodynamics	304
7.2.1	Conservation Laws	305
7.2.2	Conservative Discretization Schemes	309
7.3	Energy-Momentum Algorithmic Treatment of Frictionless Impact	312
7.3.1	Discrete Contact Constraints	313
7.3.2	Spatial Discretization and Implementation	316
7.3.3	Numerical Examples	318
7.4	Introduction of Frictional and Bulk Dissipation: Energy Consistency	325
7.4.1	Coulomb Friction Model Formulation	325
7.4.2	Local Split of the Coulomb Model	331
7.4.3	Algorithmic Formulation	332
7.4.4	Energy Consistent Treatment of Bulk Inelasticity	338
7.4.5	Numerical Examples With Friction and Inelasticity	339
7.5	EM Algorithms Involving a Discontinuous Velocity Update	347
7.5.1	Temporally Discontinuous Velocity Update	348
7.5.2	Reexamination of Conservation Conditions	350
7.5.3	Contact Constraints	355
7.5.4	Summary of the Algorithm	357
7.5.5	Numerical Examples	357
8	Emerging Paradigms for Contact Surface Discretization	369
8.1	Contact Smoothing	371
8.1.1	An Alternative Variational Framework	372
8.1.2	Smoothing Strategies in Two Dimensions	374
8.1.3	Smoothing Strategies in Three Dimensions	382
8.1.4	Numerical Examples	390
8.2	Mortar-Finite Element Methods for Contact Description	404
8.2.1	Tied Contact and the Role of Mortar Formulations in Convergence	404
8.2.2	A Mortar-Finite Element Formulation of Frictional Contact	416
8.2.3	Numerical Examples of Mortar Treatment of Frictional Contact	425

References	435
Index	451